

## MC14017B

### Decade Counter

The MC14017B is a five-stage Johnson decade counter with built-in code converter. High speed operation and spike-free outputs are obtained by use of a Johnson decade counter design. The ten decoded outputs are normally low, and go high only at their appropriate decimal time period. The output changes occur on the positive-going edge of the clock pulse. This part can be used in frequency division applications as well as decade counter or decimal decode display applications.

- Fully Static Operation
- DC Clock Input Circuit Allows Slow Rise Times
- Carry Out Output for Cascading
- Divide-by-N Counting
- Supply Voltage Range = 3.0 Vdc to 18 Vdc
- Capable of Driving Two Low-power TTL Loads or One Low-power Schottky TTL Load Over the Rated Temperature Range
- Pin-for-Pin Replacement for CD4017B
- Triple Diode Protection on All Inputs

#### MAXIMUM RATINGS\* (Voltages Referenced to V<sub>SS</sub>)

Symbol	Parameter	Value	Unit
V <sub>DD</sub>	DC Supply Voltage	– 0.5 to + 18.0	V
V <sub>in</sub> , V <sub>out</sub>	Input or Output Voltage (DC or Transient)	– 0.5 to V <sub>DD</sub> + 0.5	V
I <sub>in</sub> , I <sub>out</sub>	Input or Output Current (DC or Transient), per Pin	± 10	mA
P <sub>D</sub>	Power Dissipation, per Package†	500	mW
T <sub>stg</sub>	Storage Temperature	– 65 to + 150	°C
T <sub>L</sub>	Lead Temperature (8-Second Soldering)	260	°C

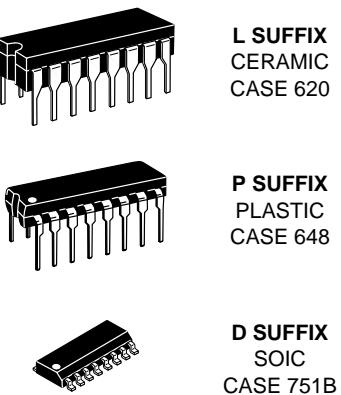
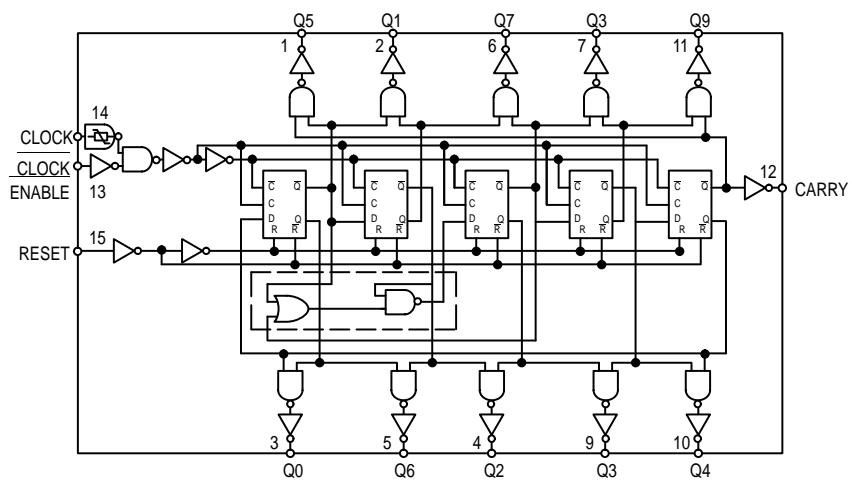
\* Maximum Ratings are those values beyond which damage to the device may occur.

†Temperature Derating:

Plastic "P and D/DW" Packages: – 7.0 mW/°C From 65°C To 125°C

Ceramic "L" Packages: – 12 mW/°C From 100°C To 125°C

#### LOGIC DIAGRAM



#### ORDERING INFORMATION

MC14XXXBCP	Plastic
MC14XXXBCL	Ceramic
MC14XXXBD	SOIC

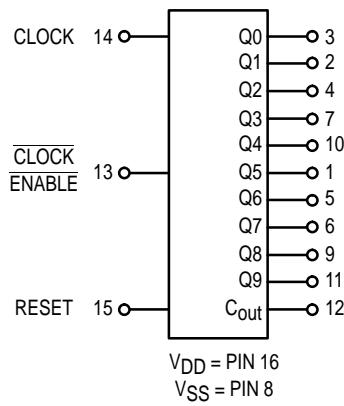
T<sub>A</sub> = – 55° to 125°C for all packages.

#### FUNCTIONAL TRUTH TABLE (Positive Logic)

Clock	Clock Enable	Reset	Decode Output=n
0	X	0	n
X	1	0	n
X	X	1	Q0
✓	0	0	n+1
✗	X	0	n
X	✓	0	n
1	✗	0	n+1

X = Don't Care. If n < 5 Carry = "1", Otherwise = "0".

#### BLOCK DIAGRAM





**SWITCHING CHARACTERISTICS\*** ( $C_L = 50 \text{ pF}$ ,  $T_A = 25^\circ\text{C}$ )

Characteristic	Symbol	$V_{DD}$ $V_{dc}$	Min	Typ #	Max	Unit
Output Rise and Fall Time $t_{TLH}, t_{TTHL} = (1.5 \text{ ns/pF}) C_L + 25 \text{ ns}$ $t_{TLH}, t_{TTHL} = (0.75 \text{ ns/pF}) C_L + 12.5 \text{ ns}$ $t_{TLH}, t_{TTHL} = (0.55 \text{ ns/pF}) C_L + 9.5 \text{ ns}$	$t_{TLH},$ $t_{TTHL}$	5.0 10 15	— — —	100 50 40	200 100 80	ns
Propagation Delay Time Reset to Decode Output $t_{PLH}, t_{PHL} = (1.7 \text{ ns/pF}) C_L + 415 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.66 \text{ ns/pF}) C_L + 197 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.5 \text{ ns/pF}) C_L + 150 \text{ ns}$	$t_{PLH},$ $t_{PHL}$	5.0 10 15	— — —	500 230 175	1000 460 350	ns
Propagation Delay Time Clock to $C_{out}$ $t_{PLH}, t_{PHL} = (1.7 \text{ ns/pF}) C_L + 315 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.66 \text{ ns/pF}) C_L + 142 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.5 \text{ ns/pF}) C_L + 100 \text{ ns}$	$t_{PLH},$ $t_{PHL}$	5.0 10 15	— — —	400 175 125	800 350 250	ns
Propagation Delay Time Clock to Decode Output $t_{PLH}, t_{PHL} = (1.7 \text{ ns/pF}) C_L + 415 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.66 \text{ ns/pF}) C_L + 197 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.5 \text{ ns/pF}) C_L + 150 \text{ ns}$	$t_{PLH},$ $t_{PHL}$	5.0 10 15	— — —	500 230 175	1000 460 350	ns
Turn-Off Delay Time Reset to $C_{out}$ $t_{PLH} = (1.7 \text{ ns/pF}) C_L + 315 \text{ ns}$ $t_{PLH} = (0.66 \text{ ns/pF}) C_L + 142 \text{ ns}$ $t_{PLH} = (0.5 \text{ ns/pF}) C_L + 100 \text{ ns}$	$t_{PLH}$	5.0 10 15	— — —	400 175 125	800 350 250	ns
Clock Pulse Width	$t_{w(H)}$	5.0 10 15	250 100 75	125 50 35	— — —	ns
Clock Frequency	$f_{cl}$	5.0 10 15	— — —	5.0 12 16	2.0 5.0 6.7	MHz
Reset Pulse Width	$t_{w(H)}$	5.0 10 15	500 250 190	250 125 95	— — —	ns
Reset Removal Time	$t_{rem}$	5.0 10 15	750 275 210	375 135 105	— — —	ns
Clock Input Rise and Fall Time	$t_{TLH},$ $t_{TTHL}$	5.0 10 15	No Limit			—
Clock Enable Setup Time	$t_{su}$	5.0 10 15	350 150 115	175 75 52	— — —	ns
Clock Enable Removal Time	$t_{rem}$	5.0 10 15	420 200 140	260 100 70	— — —	ns

\* The formulas given are for the typical characteristics only at  $25^\circ\text{C}$ .

#Data labelled "Typ" is not to be used for design purposes but is intended as an indication of the IC's potential performance.

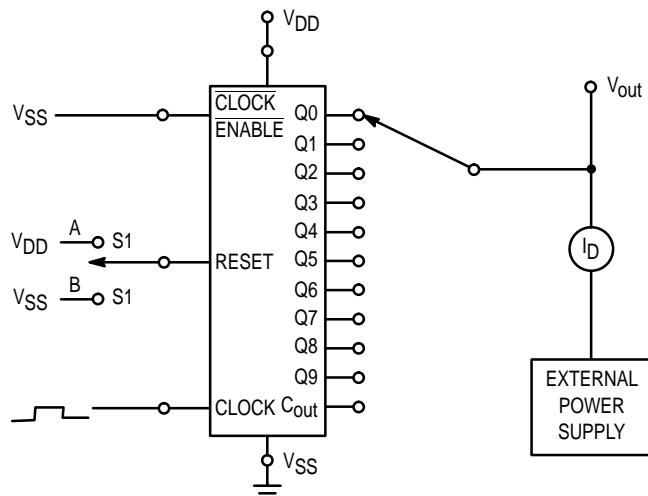


Figure 1. Typical Output Source and Output Sink Characteristics Test Circuit

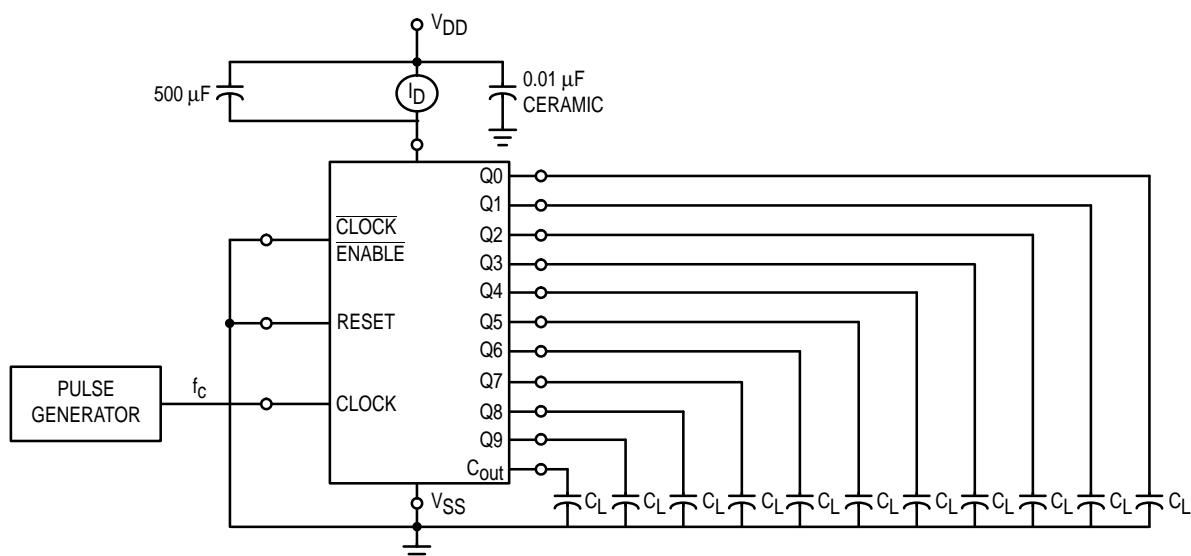


Figure 2. Typical Power Dissipation Test Circuit

## APPLICATIONS INFORMATION

Figure 3 shows a technique for extending the number of decoded output states for the MC14017B. Decoded outputs are sequential within each stage and from stage to stage, with no dead time (except propagation delay).

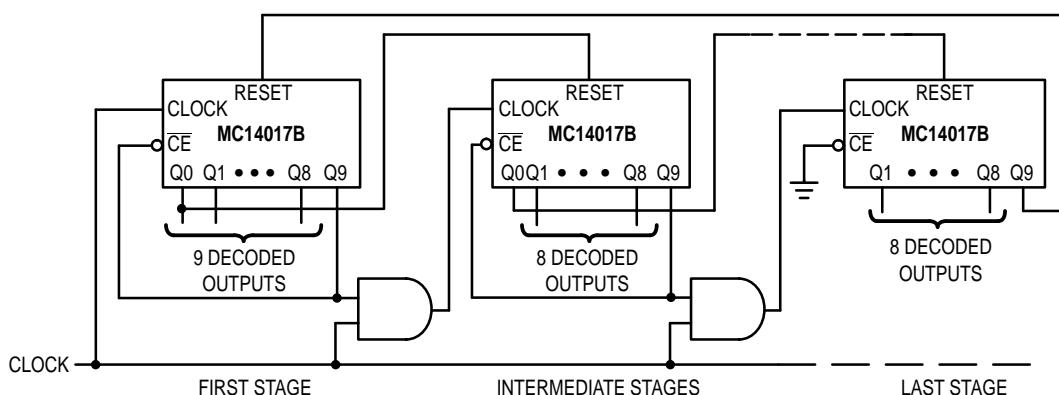
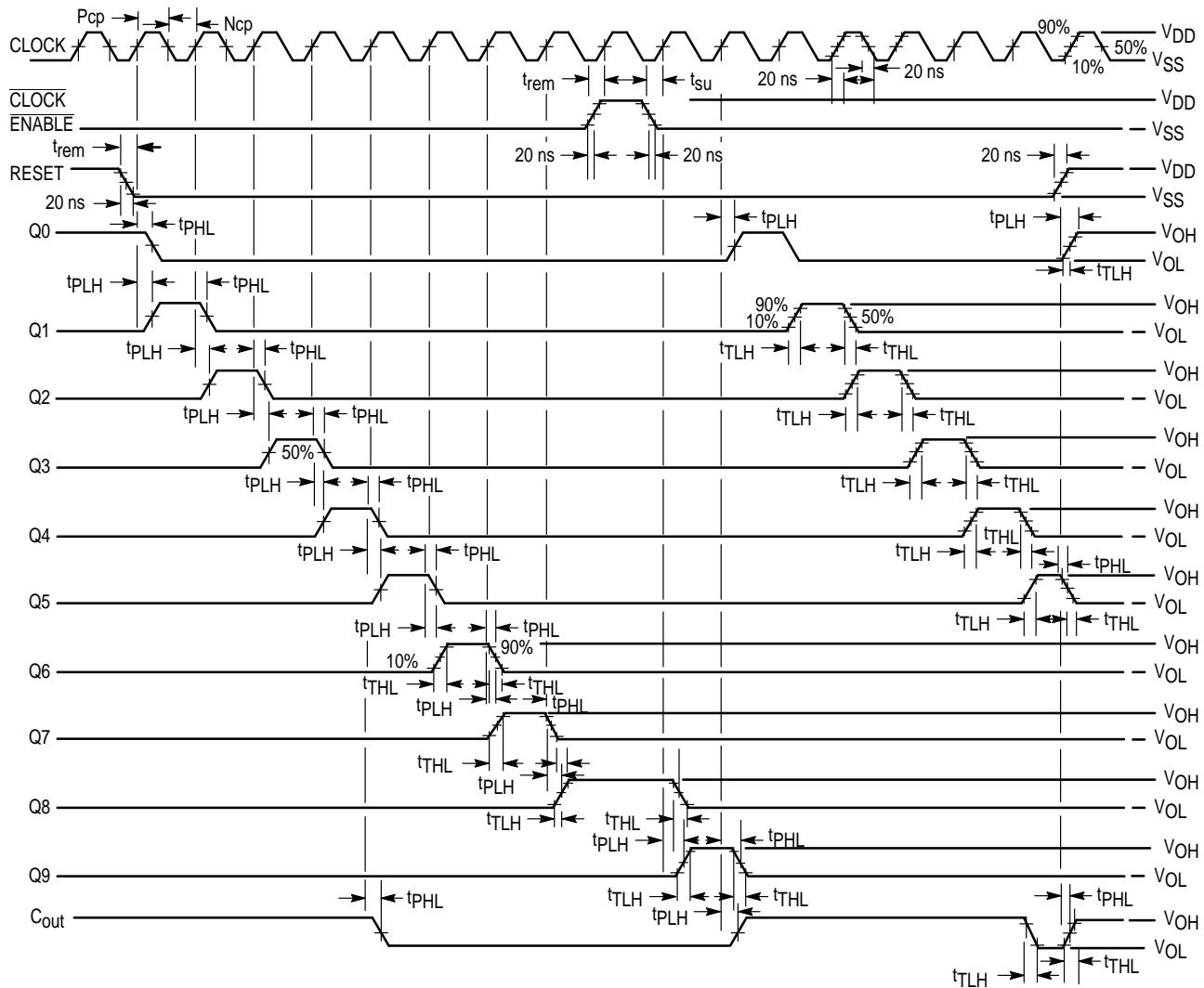


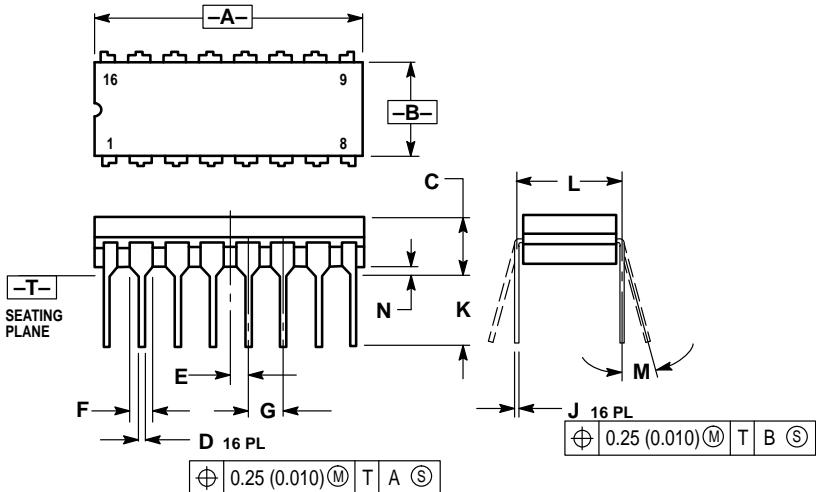
Figure 3. Counter Expansion



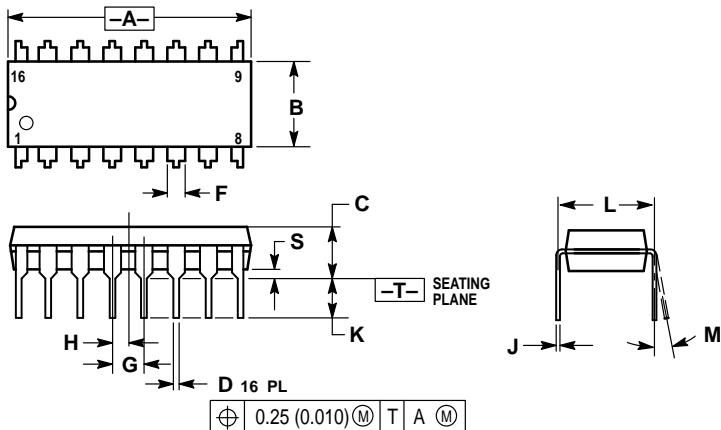
**Figure 4. AC Measurement Definition and Functional Waveforms**

## OUTLINE DIMENSIONS

**L SUFFIX**  
CERAMIC DIP PACKAGE  
CASE 620-10  
ISSUE V

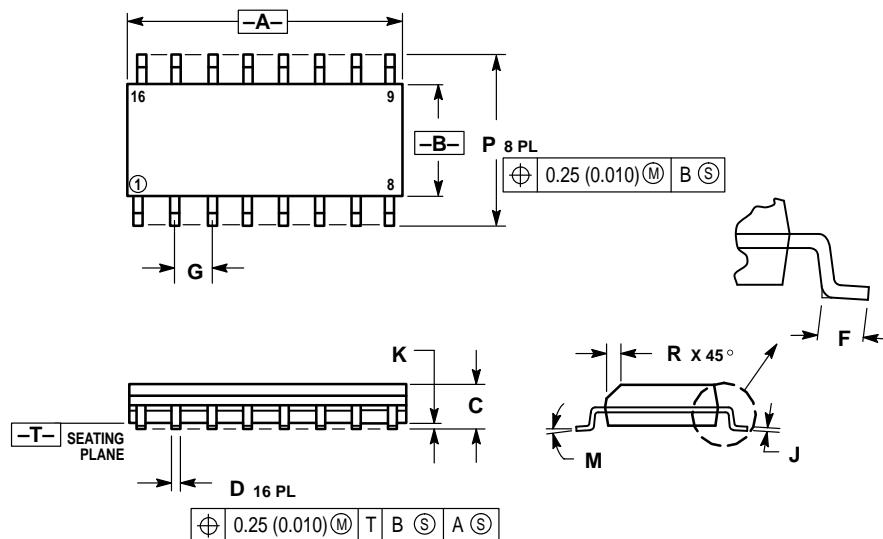


**P SUFFIX**  
PLASTIC DIP PACKAGE  
CASE 648-08  
ISSUE R



## OUTLINE DIMENSIONS

**D SUFFIX**  
**PLASTIC SOIC PACKAGE**  
**CASE 751B-05**  
**ISSUE J**



NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	9.80	10.00	0.386	0.393
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

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MC14017B/D



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